

$$P(A=b | B=b) = \frac{P(B=b | A=b) \cdot P(A=b)}{P(B=b)}$$

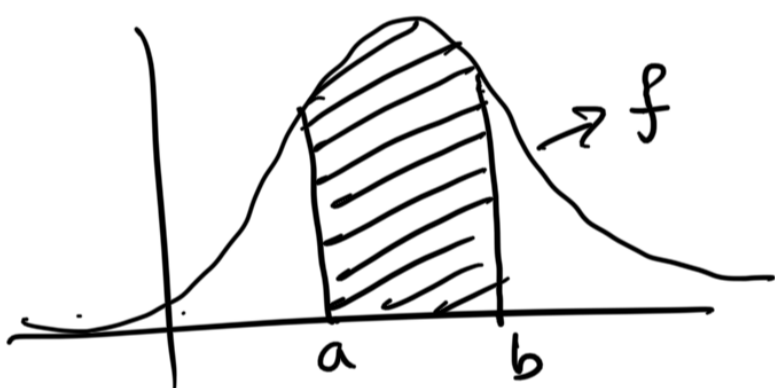
$$= \frac{P(B=b | A=b) \cdot P(A=b)}{P(B=b | A=b) \cdot P(A=b) + P(B=b | A=a) \cdot P(A=a)}$$

2/3 B

$$= \frac{\left(\frac{2}{4}\right) \cdot \left(\frac{3}{5}\right)}{\left(\frac{2}{4}\right) \cdot \left(\frac{3}{5}\right) + \left(\frac{3}{4}\right) \cdot \left(\frac{2}{5}\right)}$$

$$= \frac{6}{6+6} = \frac{1}{2}$$

$P(A=a)$  → Prob. density → PMF ~~prob~~ prob mass fn (discrete events)  
 → cont variable → PDF prob. density fn.



$$P(a \leq X \leq b)$$

$$= \int_a^b f(x) dx$$

$P(A=a) = 2/5$   
 $P(A=b) = 3/5$  } PDF of A picking a ball

$$\textcircled{1} f(x) = e^x$$

input  $x \in \mathbb{R}$   
output  $f(x) \in \mathbb{R}$

$$\frac{df(x)}{dx} = e^x$$

$$\textcircled{2} f(\vec{x}) = 3x^2y$$

$\vec{x} \in \mathbb{R}^n$   $n=2$   
 $f(x) \in \mathbb{R}$

$$\textcircled{3} f(x) = \lceil 2x \rceil$$

$x \in \mathbb{R}^n$   $n=2$

(3)  $f(x) = [3x^2]$

$f(x) \in \mathbb{R}$

(4)  $\bar{f}(\bar{x}) = \begin{bmatrix} 3x^2 y \\ 2x + 5y \\ 4xy \end{bmatrix}$

$\bar{x} \in \mathbb{R}^n$

$n=2$

$\bar{f}(x) \in \mathbb{R}^m$

$m=3$

$\bar{f}(\bar{x}) = \begin{bmatrix} f_1(\bar{x}) \\ f_2(\bar{x}) \\ \vdots \\ f_m(\bar{x}) \end{bmatrix} = \begin{bmatrix} \text{---} \end{bmatrix}$

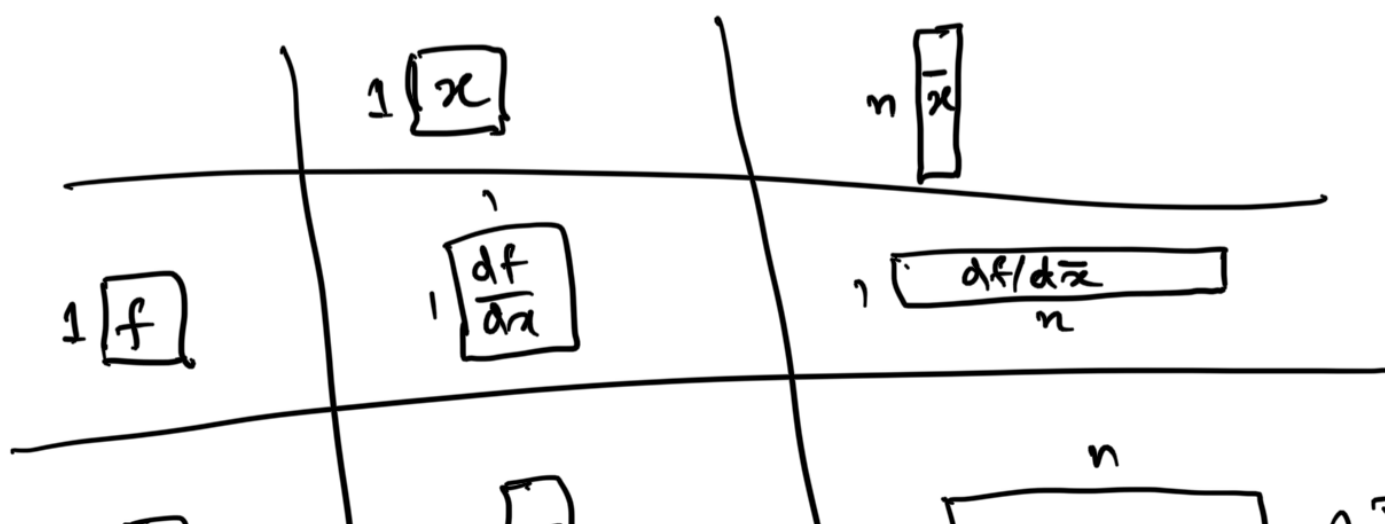
$\bar{f} \in \mathbb{R}^m$   
 $\bar{x} \in \mathbb{R}^n$

$\frac{d\bar{f}(\bar{x})}{d\bar{x}} = \begin{bmatrix} \frac{\partial}{\partial \bar{x}} f_1(\bar{x}) \\ \frac{\partial}{\partial \bar{x}} f_2(\bar{x}) \\ \vdots \\ \frac{\partial}{\partial \bar{x}} f_m(\bar{x}) \end{bmatrix}$

$= \begin{bmatrix} \frac{\partial}{\partial x_1} f_1(\bar{x}) & \frac{\partial}{\partial x_2} f_1(\bar{x}) & \dots & \frac{\partial}{\partial x_n} f_1(\bar{x}) \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial}{\partial x_1} f_m(\bar{x}) & \dots & \dots & \frac{\partial}{\partial x_n} f_m(\bar{x}) \end{bmatrix}$

Jacobian Matrix

Numerator layout of vector Gradients



$$m \begin{bmatrix} \bar{f} \\ \bar{f} \end{bmatrix} \quad \left| \quad m \begin{bmatrix} \frac{d\bar{f}}{d\bar{x}} \\ \frac{d\bar{f}}{d\bar{x}} \end{bmatrix} \right. \quad \left. \begin{matrix} m \\ \frac{d\bar{f}}{d\bar{x}} \end{matrix} \right) \rightarrow \text{JACOBIAN}$$

$$\bar{y} = A \bar{x} \quad \bar{y} \in \mathbb{R}^m \quad \bar{x} \in \mathbb{R}^n$$

$$A \in \mathbb{R}^{m \times n}$$

$$\frac{d\bar{y}}{d\bar{x}} = A$$

$$\alpha = \bar{y}^T A \bar{x} \quad \bar{y} \in \mathbb{R}^{m \times 1} \quad \bar{x} \in \mathbb{R}^{n \times 1}$$

$$A \in \mathbb{R}^{m \times n} \quad \alpha \in \mathbb{R}$$

$$\frac{\partial \alpha}{\partial \bar{x}} = \bar{y}^T A$$

$\underbrace{\hspace{10em}}_n$

$$\frac{\partial \alpha}{\partial \bar{y}} = (A \bar{x})^T = \bar{x}^T A^T$$

$\underbrace{\hspace{10em}}_m \quad (1 \times m)$

$$(1 \times m) (m \times n) = (1 \times n)$$

$$(m \times n) (n \times 1) = (m \times 1)^T$$

$$\alpha^T = \bar{x}^T A^T \bar{y}$$

$$\frac{\partial \alpha^T}{\partial \bar{y}} = \bar{x}^T A^T$$

$$\alpha = \bar{x}^T A \bar{x}$$

$$\frac{\partial \alpha}{\partial \bar{x}} = \bar{x}^T (A + A^T)$$

$\underbrace{\hspace{10em}}_n$