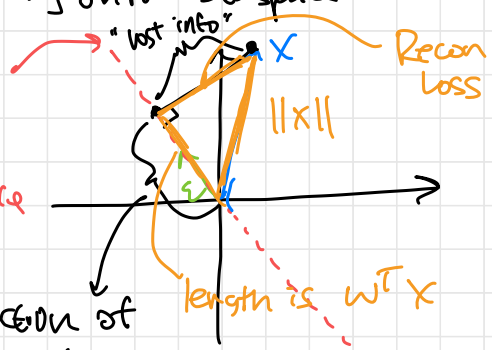


"Reconstruction Error": How well can we reconstruct $\{x^{(1)}, \dots, x^{(n)}\}$ based on only the projections of $\{x^{(1)}, \dots, x^{(n)}\}$ onto subspace defined by w

minimize

$$\sum_{i=1}^n \|x^{(i)} - (w^T x^{(i)})w\|^2$$

goal: make this "lost info" as little as possible



Projection of x onto subspace spanned by w

$$= (w^T x) \cdot w$$

How far in direction of w is x ?

Pythagorean Theorem: $(w^T x)^2 + (\text{Recon loss})^2 = \|x\|^2$

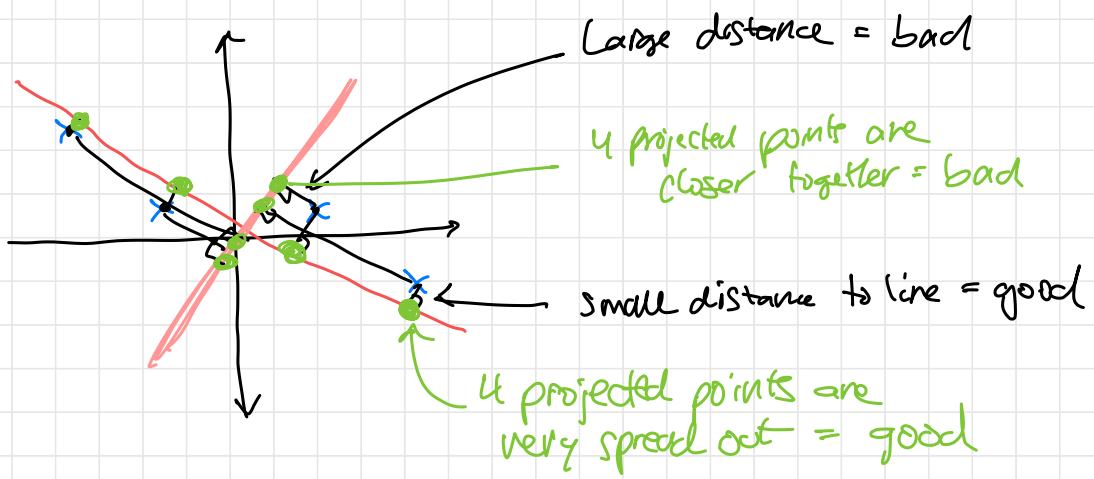
equivalent to maximize this!
minimize this
fixed

Equivalent goal: Maximize $\sum_{i=1}^n (w^T x^{(i)})^2$

Note: $\frac{1}{n} \sum_{i=1}^n (w^T x^{(i)} - \mathbb{E}[w^T x^{(i)}])^2$

is variance of $w^T x^{(i)}$

Same as maximizing variance of $w^T x^{(i)}$'s



Find w to maximize $\frac{1}{n} \sum_{i=1}^n (w^T x^{(i)})^2$

$$= \frac{1}{n} \sum_{i=1}^n \underbrace{(w^T x^{(i)})}_{1 \times 1} \underbrace{(x^{(i)T} w)}_{1 \times 1}$$

by associativity

$$= \frac{1}{n} \sum_{i=1}^n \underbrace{w^T}_{1 \times d} \underbrace{(x^{(i)} x^{(i)T})}_{d \times d} \underbrace{w}_{d \times 1}$$

$$= w^T \left(\underbrace{\frac{1}{n} \sum_{i=1}^n x^{(i)} x^{(i)T}}_{\text{Covariance matrix}} \right) w$$

in general, covariance matrix

$$\Sigma = \frac{1}{n} \sum_{i=1}^n (x^{(i)} - \bar{x}) (x^{(i)} - \bar{x})^T$$

$$= w^T \underbrace{\Sigma}_{\text{symmetric}} w$$

(because Covariance between A & B = Covariance between B & A)

Every symmetric matrix Σ can be written as

$$\Sigma = UDU^T \quad \text{where } D = \begin{bmatrix} \lambda_1 & & & 0 \\ & \lambda_2 & & \\ & & \ddots & \\ 0 & & & \lambda_n \\ & & & & 0 \end{bmatrix}$$

and U is orthogonal matrix

is diagonal
eigenvalues

$$\begin{bmatrix} | & | & & | \\ u_1 & u_2 & \dots & u_d \\ | & | & & | \end{bmatrix}$$

eigenvectors

Each column u_i has $\|u_i\| = 1$
and $u_i^T u_j = 0$ for all $i \neq j$
(i.e. orthogonal)

Now: maximize $w^T \Sigma w \Leftrightarrow \max \underbrace{w^T U}_{a^T} D \underbrace{U^T w}_a$

define $a = U^T w$.

$\|a\| = 1$ because $\|w\| = 1$
and U is orthogonal

\Rightarrow maximize $a^T D a$

$$= \sum_{j=1}^d \lambda_j a_j^2 \quad \text{subject to} \quad \sum_{j=1}^d a_j^2 = 1$$

Optimal solution: choose $a_j = 1$ for λ_j that is the largest eigenvalue

$a_j = 0$ else

Alternatively: Sort all the eigenvalues so that

$$\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_d$$

then best choice of $a = \begin{bmatrix} 1 \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$

Find w : Solve for

$$a = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} = U^T w$$

Solution is:

$$w = u_1$$

$$\begin{bmatrix} u_1^T \\ u_2^T \\ \vdots \\ u_d^T \end{bmatrix} w = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

Overall PCA algorithm:

Given $\{x^{(1)}, \dots, x^{(n)}\}$

- ① Mean-center data
- ② Compute $\Sigma = \frac{1}{n} \sum_{i=1}^n x^{(i)} x^{(i)T}$

③ Decompose Σ into UDU^T

④ Choose w to be eigenvector corresponding to largest eigenvalue

What if we want > 1 dimension?
e.g. 2-D plots

Solution: If you want K dimensions,
use the eigenvectors corresponding to
largest K eigenvalues

$$= \begin{bmatrix} u_1^T w \\ u_2^T w \\ \vdots \\ u_d^T w \end{bmatrix}$$

Supervised Learning
Data = $\{(x^{(i)}, y^{(i)})\}_{i=1}^n$

Unsupervised Learning
Data = $\{x^{(i)}\}_{i=1}^n$

Data was handed to us
Learning algorithm did
not influence what
data was collected
"passive"

Reinforcement Learning

Learning algorithm is an agent
that can take actions

- ① Influence what data you observe Bandits ✓
- ② Influence state of the world or agent Bandits ✗

Bandit Problems:

- has actions & observations,
but no state

Casino "one-armed bandit" = slot machine

Action: Choose 1 slot machine to try

Observation: \$\$ win or lose

Medicine K different candidate medicines
w/ unknown success rates

Action: Prescribe 1 of K medicines to each new patient

Observation: Did they get better?

TikTok A bunch of videos to recommend,
new user joins with unknown preferences

Action: Recommend a video

Observation: Did user watch/like/etc...

Formalization of Bandits:

- Set of actions $\{1, \dots, K\}$
- Each action has **reward** distribution $P_a(r)$
 - ↳ unknown to learner
 - ↳ part of the environment

What thing do we want to maximize?

- Casino: \$\$
- Medicine: Patient welfare

Agent plays T rounds of a game

At each time $t = 1, \dots, T$:

- Player **chooses** action $A_t \in \{1, \dots, K\}$

- Player receives reward $R_t \sim P_{A_t}(r)$

learning algorithm
Chooses

based on

previous rewards

R_1, \dots, R_{t-1}

Goal: Maximize total reward $\sum_{t=1}^T R_t$

To evaluate a bandit algorithm, measure its **regret**
= how well you did relative to best possible strategy

Define $N(a) = \mathbb{E}_{R \sim P_a(r)} [R]$ (expected reward when choosing action a)

Optimal action $a^* = \operatorname{argmax}_{a \in \{1, \dots, K\}} N(a)$

$$\text{Regret} = \underbrace{N(a^*) \cdot T}_{\text{expected reward of optimal strategy}} - \underbrace{\mathbb{E} \left[\sum_{t=1}^T R_t \right]}_{\text{Expected reward when using our learning algorithm}}$$

Ideally, want small regret

Any good algorithm will still have non-zero regret
b/c has to try all the actions first